

Solution to Exercise: Drift

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Some constants and presets

```
In[179]:= ClearAll["Global`*"];
```

```
In[217]:=  $\mu e = 1400 \frac{(10^4)^2}{10^9}$  (* mobility in  $\frac{\mu m^2}{V \cdot ns}$  *);
```

```
In[181]:= SetOptions[Plot, {Frame → True, Filling → Axis, PlotStyle → {Thickness[0.006]},  
LabelStyle → Directive[Black, 14, FontFamily → "Arial"]}];
```

1. Field Formula

```
In[182]:= Clear[Vover, Vdepl]; (* Clear old definitions *)  
$Assumptions = {Vover > 0 && Vdepl > 0};
```

We know that the field is triangular at Vdepl and has an additional component Vover / D. So we just write it down:

```
In[184]:= Field[x_, Vover_, Vdepl_] =  $\frac{Vover}{D} + \frac{(D - x)}{D} \frac{2 Vdepl}{D}$ ; (* D in  $\mu m$ , Field in  $V / \mu m$  *)
```

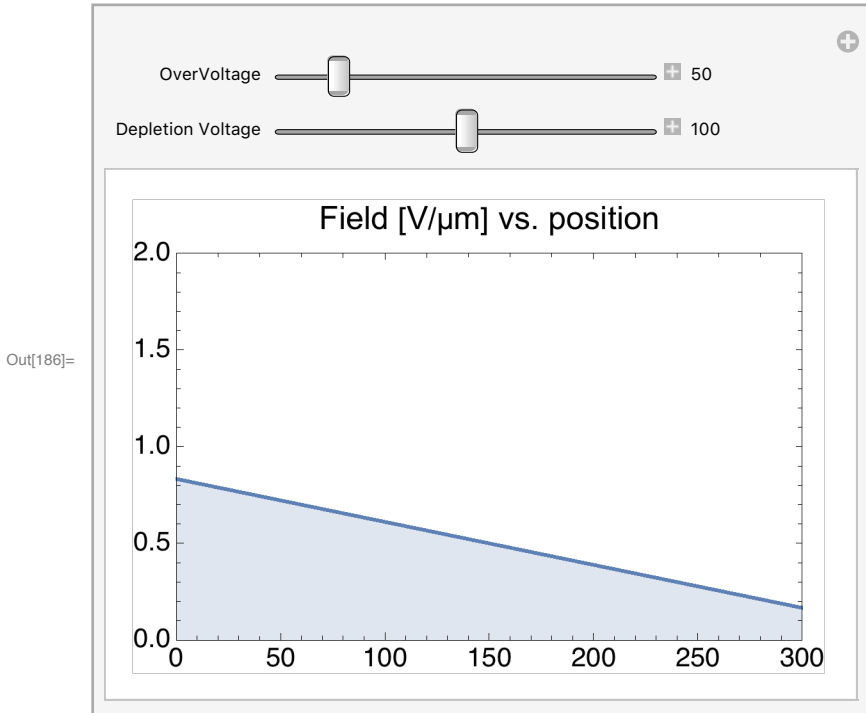
2. Check Integral

```
In[185]:= Integrate[Field[x, Vover, Vdepl], {x, 0, D}] == Vdepl + Vover
```

```
Out[185]= True
```

3. Plot

```
In[186]:= Manipulate[
  Plot[Field[x, Vover, Vdepl] /. D -> 300, {x, 0, 300},
    PlotRange -> {0, 2}, PlotLabel -> "Field [V/μm] vs. position"
  , {{Vover, 50, "OverVoltage"}, 0, 400, 10, Appearance -> "Labeled"}
  , {{Vdepl, 100, "Depletion Voltage"}, 0, 200, 10, Appearance -> "Labeled"}
]
```



4. Position as a function of time

```
In[187]:= EQ = x'[t] == μ Field[x[t], Vover, Vdepl] (* v = μ E *)
```

```
Out[187]= x'[t] == μ ( Vover/D + (2 Vdepl (D - x[t]))/D^2 )
```

```
In[188]:= DSolve[EQ, x[t], t] // First // FullSimplify
```

```
Out[188]= {x[t] -> D + (D Vover)/(2 Vdepl) + e^(- (2 t Vdepl μ)/D^2) C[1]}
```

```
In[189]:= xsolgen[t_, Vover_, Vdepl_] = x[t] /. % /. C[1] -> C (* The general solution *)
```

```
Out[189]= D + C e^(- (2 t Vdepl μ)/D^2) + (D Vover)/(2 Vdepl)
```

```
In[190]:= EQ /. {x[t] -> xsolgen[t, Vover, Vdepl], x'[t] -> D[xsolgen[t, Vover, Vdepl], t]} //
  Simplify (* Check that this solution indeed solves EQ *)
```

```
Out[190]= True
```

5. Set Initial Condition x(t=0) == 0 (* start at junction *)

```
In[191]:= Solve[xsolgen[0, Vover, Vdepl] == 0, C] //
```

```
First (* Find the integration constant from x[0] = 0 *)
```

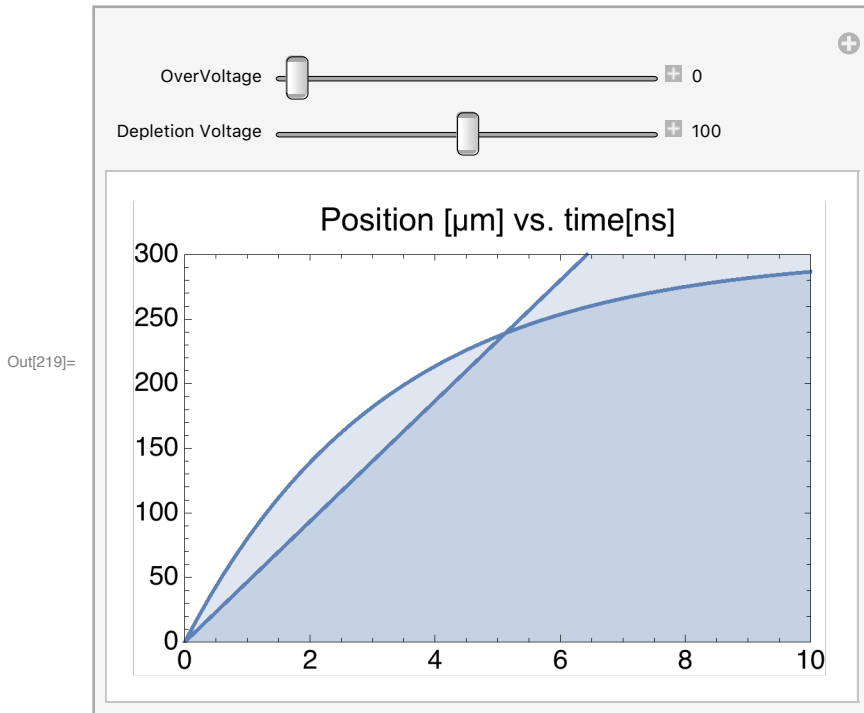
```
Out[191]= {C -> - (D (2 Vdepl + Vover))/(2 Vdepl)}
```

```
In[192]:= xsol[t_, Vover_, Vdepl_] = xsolgen[t, Vover, Vdepl] /. % // Simplify
(* xsol[t] is the solution fulfilling the initial condition *)
```

$$\text{Out[192]} = \frac{D \left(2 V_{\text{depl}} + V_{\text{over}} - e^{-\frac{2 t V_{\text{depl}} \mu}{D^2}} (2 V_{\text{depl}} + V_{\text{over}}) \right)}{2 V_{\text{depl}}}$$

```
In[193]:= xsolflat[t_, Vover_, Vdepl_] = \mu \frac{V_{\text{over}} + V_{\text{depl}}}{D} t ;
(* Trivial solution with constant field for comparison *)
```

```
In[219]:= Manipulate[
  Plot[{xsol[t, Vover, Vdepl], xsolflat[t, Vover, Vdepl]} /. {D -> 300, \mu -> \mu e}, {t, 0, 10}
    , PlotRange -> {0, 300}
    , PlotLabel -> "Position [\mu m] vs. time[ns]"
  ]
  , {{Vover, 0, "OverVoltage"}, 0, 200, 10, Appearance -> "Labeled"}
  , {{Vdepl, 100, "Depletion Voltage"}, 0, 200, 10, Appearance -> "Labeled"}
]
(* At 0 overvoltage,
the other side at D=300 is never reached because the field is 0 there *)
```



```
In[220]:= xsol[t, Vover, Vdepl] == \frac{D e^{-\frac{2 t V_{\text{depl}} \mu}{D^2}} \left( -1 + e^{\frac{2 t V_{\text{depl}} \mu}{D^2}} \right) (2 V_{\text{depl}} + V_{\text{over}})}{2 V_{\text{depl}}} // FullSimplify
```

```
Out[220]= True
```

6. Time to reach Position x in general and backside at x=D when starting at x=0.

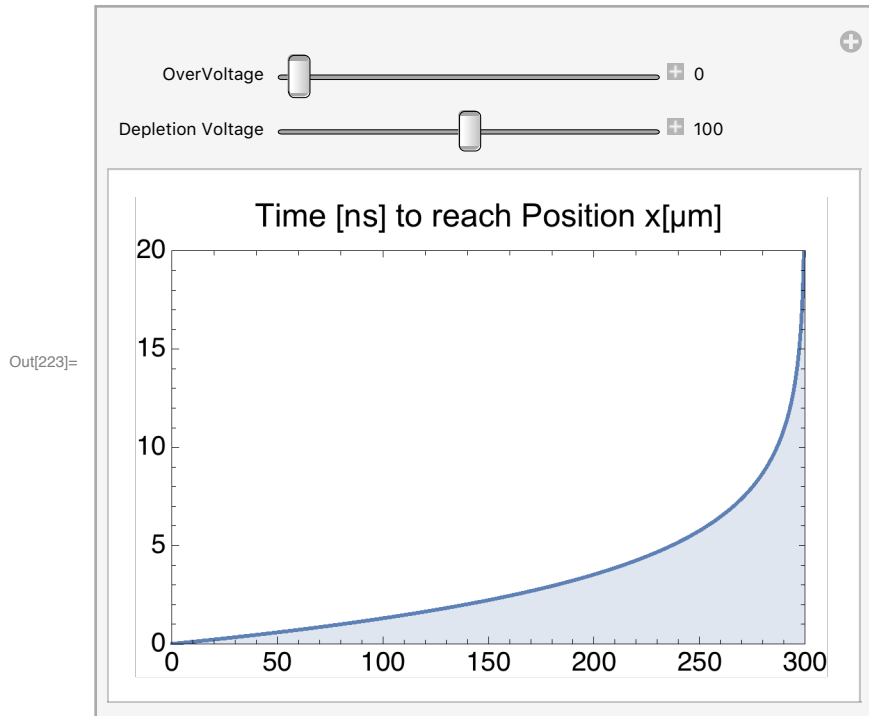
```
In[221]:= tsol = Solve[x == xsol[t, Vover, Vdepl], t] // First
```

$$\text{Out[221]} = \left\{ t \rightarrow \text{ConditionalExpression} \left[\frac{D^2 \left(2 i \pi C[1] + \text{Log} \left[\frac{D (2 V_{\text{depl}} + V_{\text{over}})}{2 D V_{\text{depl}} + D V_{\text{over}} - 2 V_{\text{depl}} x} \right] \right)}{2 V_{\text{depl}} \mu}, C[1] \in \mathbb{Z} \right] \right\}$$

In[222]:= $t[x_ , Vover_ , Vdepl_] = t /. First[Simplify[tsol, C[1] == 0]]$

Out[222]=
$$\frac{D^2 \operatorname{Log}\left[\frac{D (2 Vdepl + Vover)}{D (2 Vdepl + Vover) - 2 Vdepl x}\right]}{2 Vdepl \mu}$$

In[223]:= **Manipulate**[
Plot[{ $t[x, Vover, Vdepl]$ } /. { $D \rightarrow 300, \mu \rightarrow \mu e$ }, { $x, 0, 300$ }, **PlotRange** → {0, 20},
PlotLabel → "Time [ns] to reach Position $x[\mu m]$ "
],
{{ $Vover, 0, "OverVoltage"$ }, 0, 200, 10, **Appearance** → "Labeled"},
{{ $Vdepl, 100, "Depletion Voltage"$ }, 0, 200, 10, **Appearance** → "Labeled"}
]



In[224]:= $tdriftToD = t[D, Vover, Vdepl] // Simplify$

Out[224]=
$$\frac{D^2 \operatorname{Log}\left[1 + \frac{2 Vdepl}{Vover}\right]}{2 Vdepl \mu}$$

In[225]:= $tdriftToDflat = \frac{D x}{(Vdepl + Vover) \mu} /. x \rightarrow D;$

7. Total Drift Time to reach backside at $x=D$

In[226]:= { $tdriftToD, tdriftToDflat$ } /. { $Vdepl \rightarrow 100, Vover \rightarrow 50, \mu \rightarrow \mu e, D \rightarrow 300$ } // N

Out[226]= {5.17319, 4.28571}

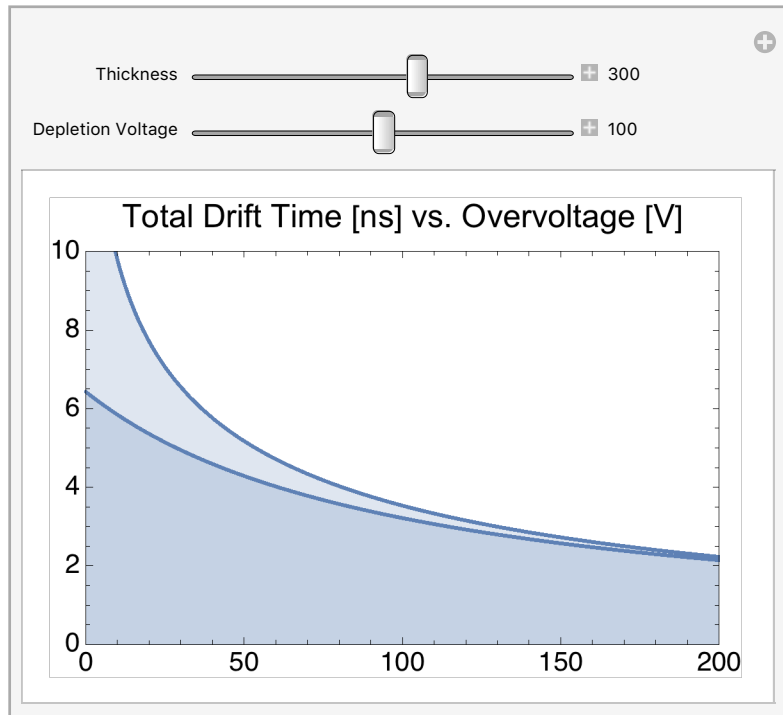
8. Plot

```

In[227]:= Manipulate[
  Plot[{tdriftToD, tdriftToDflat} /. {D → t, Vdepl → b,  $\mu \rightarrow \mu_e$ }, {Vover, 0, 200}
    , PlotRange → {0, 10}
    , PlotLabel → "Total Drift Time [ns] vs. Overvoltage [V]"
    , {{t, 300, "Thickness"}, 0, 500, 50, Appearance → "Labeled"}
    , {{b, 100, "Depletion Voltage"}, 0, 200, 10, Appearance → "Labeled"}
]

```

Out[227]=



Try Calculation with Variable Mobility - No closed solution found..